Small, light and high speed and torque 5-phase stepper motor driver

■ Features

- Bipolar constant pentagon drive method
- Includes Auto Current Down and self-diagnosis function
- Low speed rotation and high accuracy controlling with microstep-driving (Except for MD5-ND14)
  [Max. resolution - 250 division / In case of 5-phase stepper motor of which basic step angle is 0.72 , it enables to control up to 0.00288 per pulse and it requires 125,000 pulses per rotation.]
- Photocoupler input insulation method to minimize the effects from external noise



MD5-HF28 MD5-HF14 MD5-HF14-AO MD5-HD14 MD5-ND14

⚠ **Please read "Caution for your safety" in operation manual before using.**

(Except for MD5-HF14-AO, MD5-HD14, ND14)

■ Ordering information

MD 5 – H F 14 – □

Output	No mark	Zero point excitation output※1	
	AO	Alarm output	
RUN current	14	1.4A/Phase	
	28	2.8A/Phase	
Power supply	D	20-35VDC	
	F	100-220VAC	
Step type (Resolution)	H	Micro step(250divisions)	
	N	Normal Step	
Motor phase	5	5-Phase	
Item	MD	Motor Driver	

※1: Except MD5-ND14

※KR-55MC can be replaced with MD5-HD14.
※KR-5MC can be replaced with MD5-ND14.
※MD5-MF14 can be replaced with MD5-HF14.
※KR-505G can be replaced with MD5-HF28.

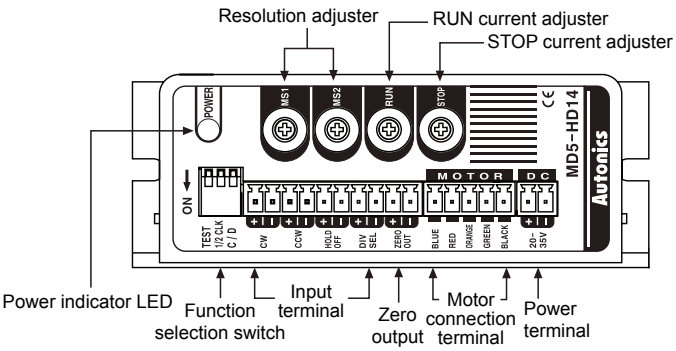
■ Specifications

Model		MD5-HD14	MD5-HF14	MD5-HF14-AO	MD5-HF28	MD5-ND14
Power supply		20-35VDC 3A※1	100-220VAC 50/60Hz			20-35VDC 3A
RUN current		0.4 to 1.4A / Phase			1.0 to 2.8A / Phase	0.5 to 1.5A / Phase
RUN method		Bipolar constant pentagon drive				
Basic step angle		0.72°/ Phase				
Resolution		1, 2, 4, 5, 8, 10, 16, 20, 25, 40, 50, 80, 100, 125, 200, 250 division (0.72°to 0.00288°/ Phase)				1, 2 division (0.72°, 0.36°/ Phase)
Input pulse width		Min. 0.5μs			0.1μs	Min. 10μs
Pulse Duty		50%				
Rising/Falling time		Max. 120ns			Max. 1μs	Max. 120ns
Max. input pulse frequency※2		1MHz			500kHz	50kHz
Input voltage level		High : 4-8VDC, Low : 0-0.5VDC				
Input resistance		270Ω(CW, CCW) 390Ω(HOLD OFF, DIVISION SELECTION)		270Ω(CW, CCW) 390Ω(HOLD OFF)	270Ω(CW, CCW) 390Ω(HOLD OFF, DIVISION SELECTION)	390Ω (CW, CCW, HOLD OFF)
Environment	Ambient temperature	0 to 40℃, storage: -20 to 60℃	0 to 50℃, storage: -10 to 60℃		0 to 40℃, storage: -20 to 60℃	
	Ambient humidity	35 to 85%RH, storage: -10 to 90%RH	35 to 85%RH, storage: 35 to 85%RH			35 to 85%RH, storage: -10 to 90%RH
Approval		CE	CE cULus	CE	CE cULus	CE
Unit weight		Approx. 220g	Approx. 660g	Approx. 650g	Approx. 1kg	Approx. 120g

※1: When using over 30VDC, it should be mounted at ventilated place due to increasing heat.
※2: Max. pull-out frequency and max. slewing frequency are variable depending on resolution, or load.
※Environment resistance is rated at no freezing of condensation.

5-Phase micro stepper motor driver [MD5-HD14]





◎ Function selection switch



NO	Name	Function	Switch position	
			ON	OFF
1	TEST	Self-diagnosis	Rotate in 30rpm	Not using
2	1/2 CLK	Pulse input method	1 Pulse input	2 Pulse input
3	C/D	Auto current down	Not using	Using

● TEST

※Self-diagnosis function is to test motors and drivers.
※Motors rotate with 30 rpm in full-step. Motor rotation speed is subject to change depending on resolution setting.
※Rotation speed = 30 rpm / resolution
※The motor will rotate in CCW direction when in 1-pulse input mode and in CW direction when in 2-pulse input mode.
Note) Make sure that TEST switch is set to OFF before supplying the power.
It may cause injury or danger if TEST switch is set to ON when power is supplied.

● 1/2 CLK

※1/2 CLK switch is to select pulse input mode.
※1-pulse input mode : CW → operation command pulse input, CCW → rotation direction pulse input
([H] : CW rotation, [L] : CCW rotation)
※2 Puls input mode : CW → CW direction rotation pulse input, CCW → CCW direction rotation pulse input

● C/D (Auto current down)

※This function is reducing current automatically according to STOP current setting value in order to suppress generated heat when motor is stop.
※It activates when there is no pulse input of motor operation for over 200ms.

◎ RUN current setting



S/W No	0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F
Current (A/Phase)	0.4	0.5	0.57	0.63	0.71	0.77	0.84	0.9	0.96	1.02	1.09	1.15	1.22	1.22	1.33	1.4

※RUN current is a phase current provided to 5-phase stepper motor.
※Be sure to set RUN current at the rated current or below.
※Adjust the RUN current in case severe heat generation occurs. Be sure that torque decreasing may occur when adjusting the current.
Note) Be sure to adjust RUN current while motor is running.

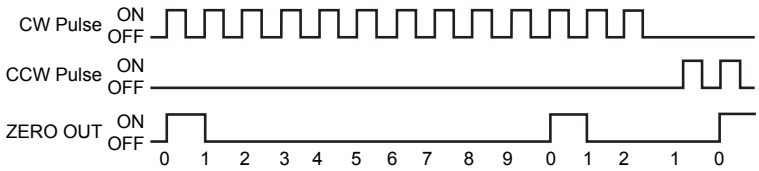
◎ STOP current setting



Switch No.	0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F
%	27	31	36	40	45	50	54	58	62	66	70	74	78	82	86	90

※STOP current is a phase current provided to 5-phase stepper motor at standstill.
※It will be activated when C/D (Auto current down) is set to ON. By setting STOP current, it is possible to suppress the heat generation at motor standstill.
※STOP current setting value is the ratio of RUN current setting value (%).
Ex) In case RUN current setting value is set to 1.4A and STOP current setting value is set to 50%, auto current down current is set to 0.7A.
※STOP current setting value may have some deviation depending on resistance impedance of motor.
※Auto current down function will be activated when HOLD OFF signal is [L]. When HOLD OFF signal is [H], the function is not activated since the current provided to each phase is cut off.
Note) Be sure to adjust STOP current while motor is at standstill.

◎ Zero point excitation output signal (ZERO OUT)



※The signal is output to indicate when the motor excitation status is in the initial stage. Used to check the rotation position of motor's axis.
※In case of full step, the signal is output every 7.2°. (50 times / rotation).
Ex) Full step (0.72°/Step) : Signal is output every 10 pulses
20 divisions (0.036°/Step) : Signal is output every 200 pulses.

◎ HOLD OFF function

※When HOLD OFF input signal is [H], motor excitation is released.
When HOLD OFF input signal is [L], motor excitation is in a normal status.
※A function used to rotate motor's axis using external force or used for manual positioning.
※HOLD OFF Input signal [H] and [L] represent photocoupler ON/OFF in a circuit.
※Please do not use for stopping motor.

◎ Setting microstep(Microstep : Resolution)



Switch No.	0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F
Resolution	1	2	4	5	8	10	16	20	25	40	50	80	100	125	200	250
Step angle	0.72°	0.36°	0.18°	0.144°	0.09°	0.072°	0.045°	0.036°	0.0288°	0.018°	0.0144°	0.009°	0.0072°	0.00576°	0.0036°	0.00288°

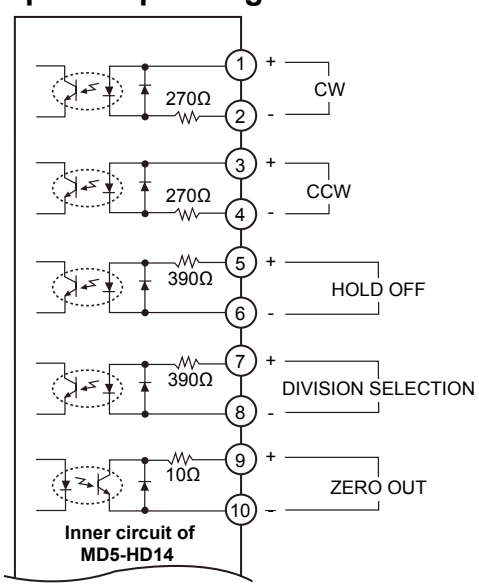
● Resolution setting(Same as MS1, MS2)

※It is set to MS1 when division selection signal is [L], and MS2 when division selection signal is [H].
※Two different micro step can be set using DIVISION SELECTION. Users can select one of them via external input signals.
※Microstep is to make basic step angle of 5-phase motors (0.72°) divided into smaller angle according to setting values.
※The formula for microstep angle is ;

$$\text{Motor revolution angle (5-phase motors)} = \frac{\text{Basic step angle(0.72°)}}{\text{Resolution}}$$

※In case of geared motors, step angle shall be determined by dividing step angle by gear ratio.
EX) 0.72˚/ 10 (1:10) = 0.072˚
※It may cause step-out if resolution is changed while motor is running.

▣ Input·Output diagram



※CW
2-pulse input mode - CW direction rotation pulse input
1-pulse input mode - Operation command pulse input

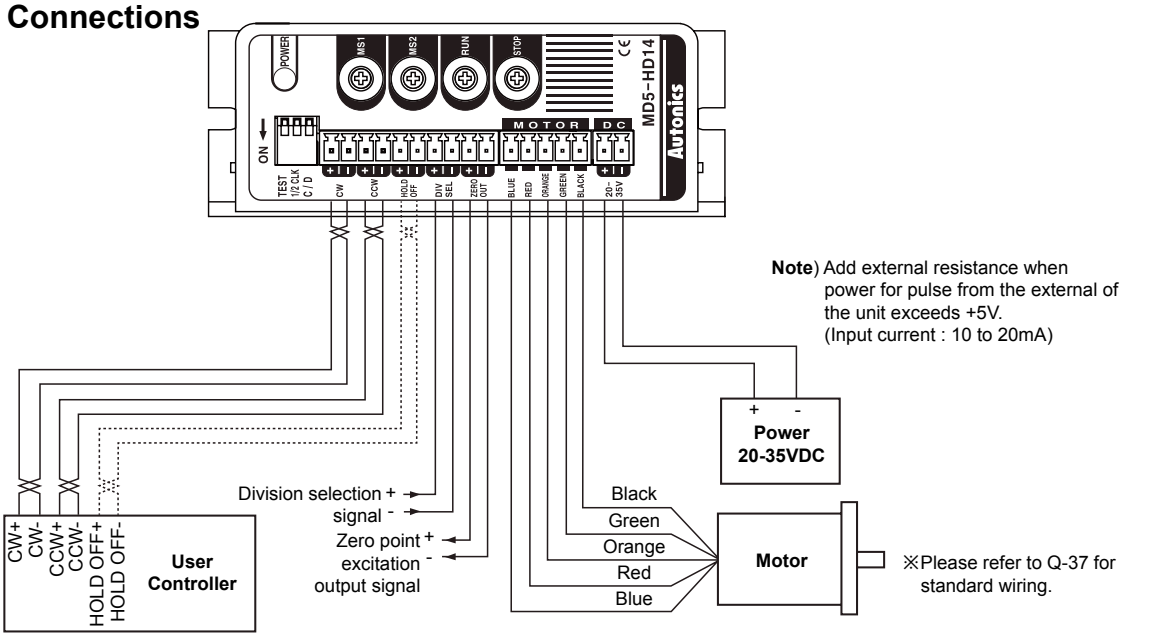
※CCW
2-pulse input mode - CCW direction rotation pulse input
1-pulse input mode - Rotation direction pulse input
[H] : CW, [L] : CCW

※HOLD OFF
Motor excitation OFF control signal
[H] : Motor excitation OFF

※DIVISION SELECTION
Division selection signal
→ [L] : Operated by MS1 setting resolution.
[H] : Operated by MS2 setting resolution.

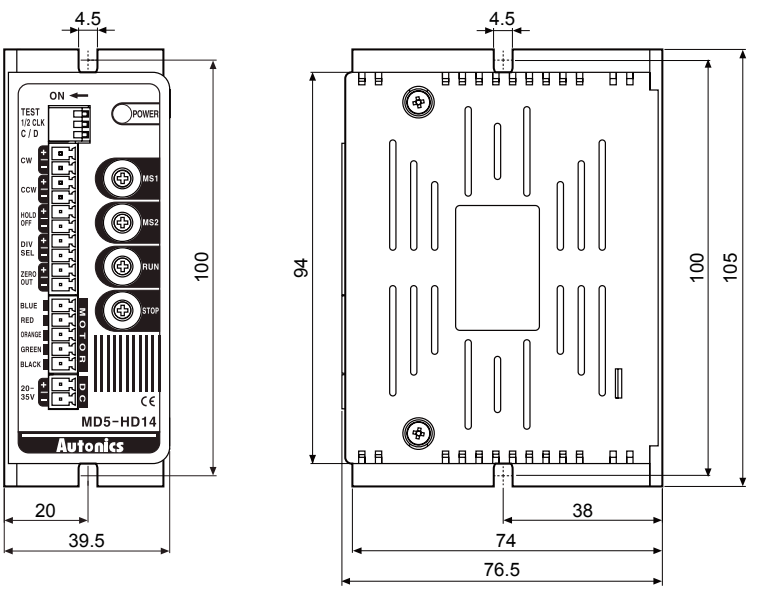
※ZERO OUT
Zero point excitation output signal ON for zero point excitation

▣ Connections



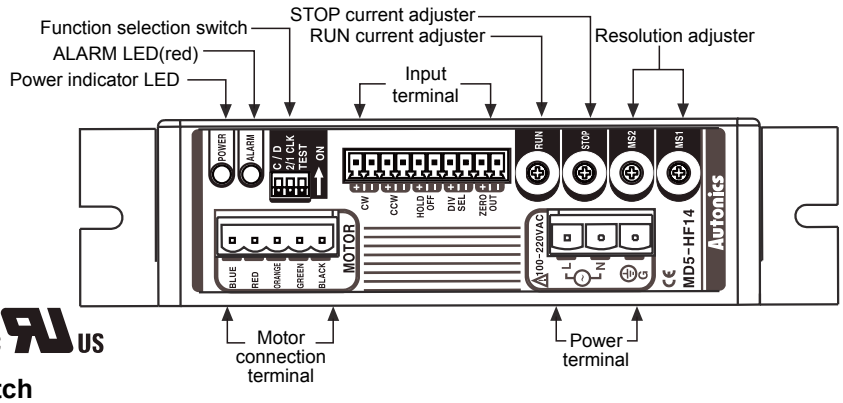
▣ Dimensions

(unit: mm)



5-Phase Micro stepper motor driver [MD5-HF14]





◎ Function selection switch



NO	Name	Function	Switch position	
			ON	OFF
1	TEST	Self-diagnosis	Rotate in 250Hz	—
2	2/1 CLK	Pulse input method	1 Pulse input	2 Pulse input
3	C/D	Auto current down	Not using	Using

●TEST

※Self-diagnosis function is to test motors and drivers.
※Motors rotate with 250Hz in full-step. Motor rotation speed is subject to change depending on resolution setting.
※Rotation speed = 30 rpm / resolution
※The motor will rotate in CCW direction when in 1-pulse input mode and in CW direction when in 2-pulse input mode.
Note) Make sure that TEST switch is set to OFF before supplying the power.
It may cause injury or danger if TEST switch is set to ON when power is supplied.

●2/1 CLK

※1/2 CLK switch is to select pulse input mode.
※1-pulse input mode : CW → operation command pulse input, CCW → rotation direction pulse input
([H]: CW rotation, [L]: CCW rotation)
※2-Puls input mode : CW → CW direction rotation pulse input, CCW → CCW direction rotation pulse input

●C/D (Auto current down)

※This function is reducing current automatically according to STOP current setting value in order to suppress generated heat when motor is stop.
※It activates when there is no pulse input of motor operation for over 200ms.



Switch No.	0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F
Current (A/Phase)	0.4	0.5	0.57	0.63	0.71	0.77	0.84	0.9	0.96	1.02	1.09	1.15	1.22	1.27	1.33	1.4

※RUN current is a phase current provided to 5-phase stepper motor.
※Be sure to set RUN current at the rated current or below.
※Adjust the RUN current in case severe heat generation occurs. Be sure that torque decreasing may occur when adjusting the current.
Note) Be sure to adjust RUN current while motor is running.

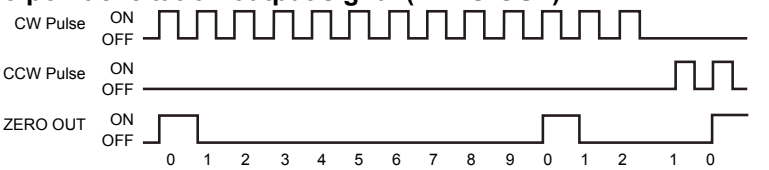
◎ STOP current setting



Switch No.	0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F
%	27	31	36	40	45	50	54	58	62	66	70	74	78	82	86	90

※STOP current is a phase current provided to 5-phase stepper motor at standstill.
※It will be activated when C/D (Auto current down) is set to ON. By setting STOP current, it is possible to suppress the heat generation at motor standstill.
※STOP current setting value is the ratio of RUN current setting value (%).
Ex) In case RUN current setting value is set to 1.4A and STOP current setting value is set to 50%, auto current down current is set to 0.7A.
※STOP current setting value may have some deviation depending on resistance impedance of motor.
※Auto current down function will be activated when HOLD OFF signal is [L]. When HOLD OFF signal is [H], the function is not activated since the current provided to each phase is cut off.
Note) Be sure to adjust STOP current while motor is at standstill.

◎ Zero point excitation output signal (ZERO OUT)



※The signal is output to indicate when the motor excitation status is in the initial stage. / Used to check the rotation position of motor's axis
※In case of full step, the signal is output every 7.2°. (50 times / rotation)
EX) Full step (0.72°/Step): Signal is output every 10 pulses.
20 divisions (0.036°/Step): Signal is output every 200 pulses.

◎ HOLD OFF function

※When HOLD OFF input signal is [H], motor excitation is released.
When HOLD OFF input signal is [L], motor excitation is in a normal status.
※A function used to rotate motor's axis using external force or used for manual positioning.
※HOLD OFF Input signal [H] and [L] represent photocoupler ON/OFF in a circuit.
※Please do not use for stopping motor.

◎ Setting microstep(Microstep : Resolution)



Switch No.	0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F
Resolution	1	2	4	5	8	10	16	20	25	40	50	80	100	125	200	250
Step angle	0.72°	0.36°	0.18°	0.144°	0.09°	0.072°	0.045°	0.036°	0.0288°	0.018°	0.0144°	0.009°	0.0072°	0.00576°	0.0036°	0.00288°

• Resolution setting(Same as MS1, MS2)

※It is set to MS1 when division selection signal is [L], and MS2 when division selection signal is [H].
※Two different micro step can be set using DIVISION SELECTION. Users can select one of them via external input signals.
※Microstep is to make basic step angle of 5-phase motors (0.72°) divided into smaller angle according to setting values.
※The formula for microstep angle is ;

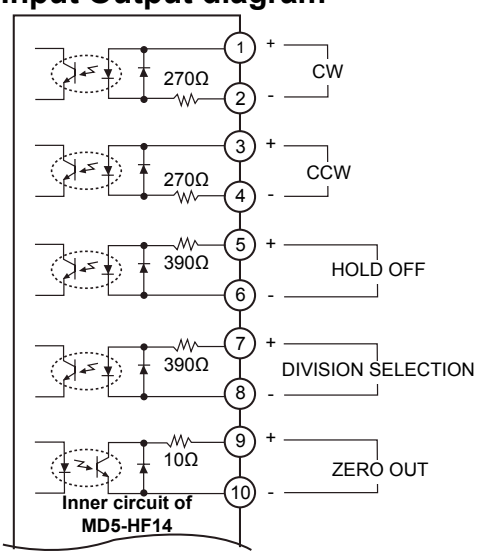
$$\text{Motor revolution angle (5-phase motors)} = \frac{\text{Basic step angle(0.72°)}}{\text{Resolution}}$$

※In case of geared motors, step angle shall be determined by dividing step angle by gear ratio.
EX) 0.72˚/ 10 (1:10) = 0.072˚
※It may cause step-out if resolution is changed while motor is running.

◎ ALRAM Function

※Over heat: When the temperature in driver BASE is over 80℃, Alarm LED will be ON and motor will stop with holding the torque. Remove the Over Heat Alarm causing factors and reset the power in order to reset alarm function.
※Overcurrent: When overcurrent is applied to the motor due to driver damage or errors, Alarm LED will be flickering. In case of overcurrent, the motor will be HOLD OFF. Cut off the power and remove overcurrnet-causing factors in order to resume normal operation.

▣ Input·Output diagram



※CW
2-pulse input mode - CW direction rotation pulse input
1-pulse input mode - Operation command pulse input

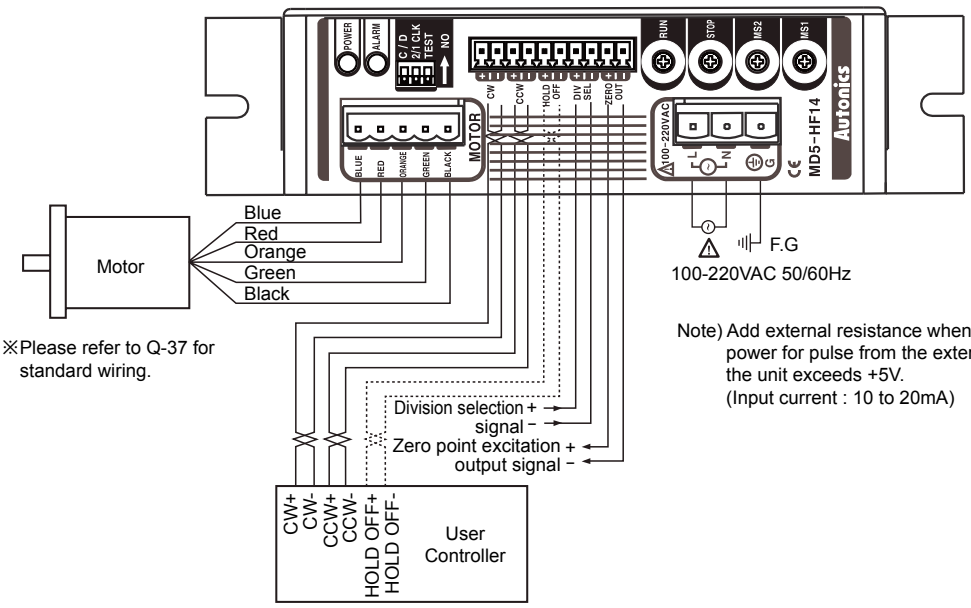
※CCW
2-pulse input mode - CCW direction rotation pulse input
1-pulse input mode - rotation direction pulse input
[H] : CW, [L] : CCW

※HOLD OFF
Motor excitation OFF control signal
[H] : Motor excitation OFF

※DIVISION SELECTION
Division selection signal
→ [L] : Operated by MS1 setting resolution.
[H] : Operated by MS2 setting resolution.

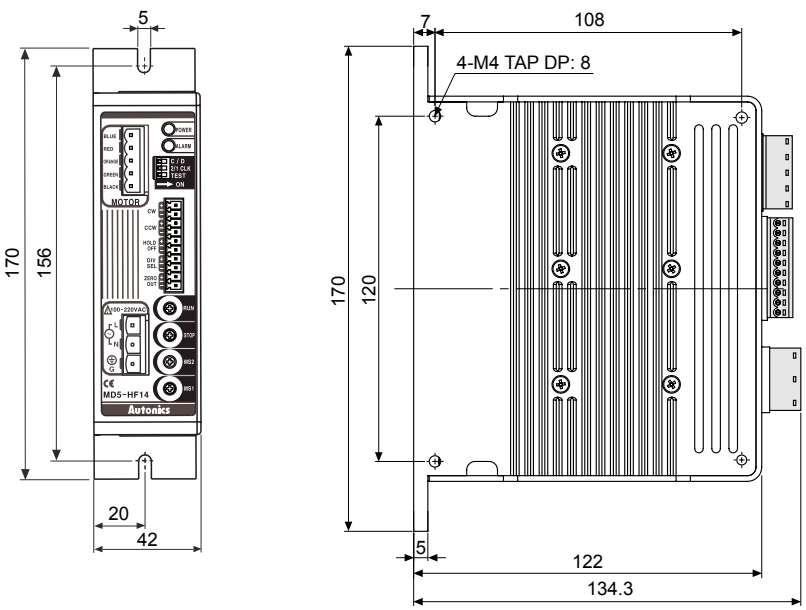
※ZERO OUT
Zero point excitation output signal ON for zero point excitation

▣ Connections



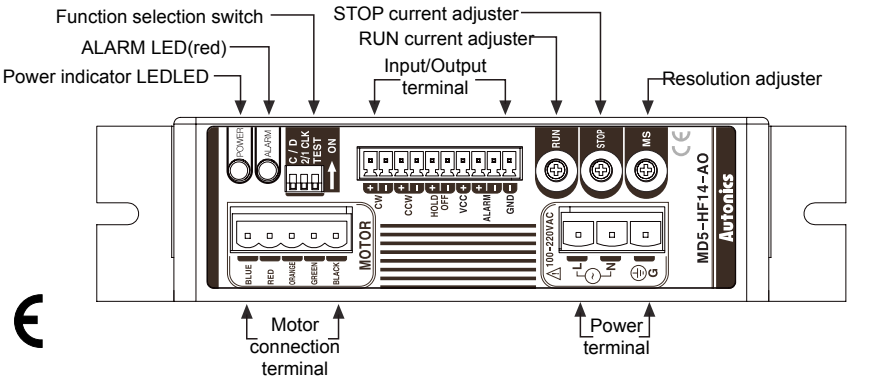
▣ Dimensions

(unit: mm)



5-Phase Micro stepper motor driver [MD5-HF14-AO]





◎ Function selection switch



NO	Name	Function	Switch position	
			ON	OFF
1	TEST	Self-diagnosis	Rotate in 30rpm	—
2	2/1 CLK	Pulse input method	1 Pulse input	2 Pulse input
3	C/D	Auto current down	Not using	Using

● TEST

※Self-diagnosis function is to test motors and drivers.

※Motors rotate with 30 rpm in full-step. Motor rotation speed is subject to change depending on resolution setting.

※Rotation speed = 30 rpm / resolution

※The motor will rotate in CCW direction when in 1-pulse input mode and in CW direction when in 2-pulse input mode.

Note) Make sure that TEST switch is set to OFF before supplying the power.
It may cause injury or danger if TEST switch is set to ON when power is supplied.

● 2/1 CLK

※1/2 CLK switch is to select pulse input mode.

※1-pulse input mode : CW → operation command pulse input, CCW → rotation direction pulse input
([H]: CW rotation, [L]: CCW rotation)

※2 Pulse input mode : CW → CW direction rotation pulse input, CCW → CCW direction rotation pulse input

● C/D (Auto current down)

※This function is reducing current automatically according to STOP current setting value in order to suppress generated heat when motor is stop.

※It activates when there is no pulse input of motor operation for over 200ms.

◎ RUN current setting



Switch No.	0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F
Current (A/Phase)	0.4	0.5	0.57	0.63	0.71	0.77	0.84	0.9	0.96	1.02	1.09	1.15	1.22	1.27	1.33	1.4

※RUN current is a phase current provided to 5-phase stepper motor.

※Be sure to set RUN current at the rated current or below.

※Adjust the RUN current in case severe heat generation occurs. Be sure that torque decreasing may occur when adjusting the current.

Note) Be sure to adjust RUN current while motor is running.

◎ STOP current setting



Switch No.	0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F
%	27	31	36	40	45	50	54	58	62	66	70	74	78	82	86	90

※STOP current is a phase current provided to 5-phase stepper motor at standstill.

※It will be activated when C/D (Auto current down) is set to ON. By setting STOP current, it is possible to suppress the heat generation at motor standstill.

※STOP current setting value is the ratio of RUN current setting value (%).

Ex) In case RUN current setting value is set to 1.4A and STOP current setting value is set to 50%, auto current down current is set to 0.7A.

※STOP current setting value may have some deviation depending on resistance impedance of motor.

※Auto current down function will be activated when HOLD OFF signal is [L]. When HOLD OFF signal is [H], the function is not activated since the current provided to each phase is cut off.

Note) Be sure to adjust STOP current while motor is at standstill.

◎ HOLD OFF function

※When HOLD OFF input signal is [H], motor excitation is released.
When HOLD OFF input signal is [L], motor excitation is in a normal status.
※A function used to rotate motor's axis using external force or used for manual positioning.
※HOLD OFF Input signal [H] and [L] represent photocoupler ON/OFF in a circuit.
※Please do not use for stopping motor.

◎ Setting microstep(Microstep : Resolution)



Switch No.	0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F
Resolution	1	2	4	5	8	10	16	20	25	40	50	80	100	125	200	250
Step angle	0.72°	0.36°	0.18°	0.144°	0.09°	0.072°	0.045°	0.036°	0.0288°	0.018°	0.0144°	0.009°	0.0072°	0.00576°	0.0036°	0.00288°

● Resolution setting

※Microstep is to make basic step angle of 5-phase motors (0.72°) divided into smaller angle according to setting values.
※The formula for microstep angle is ;

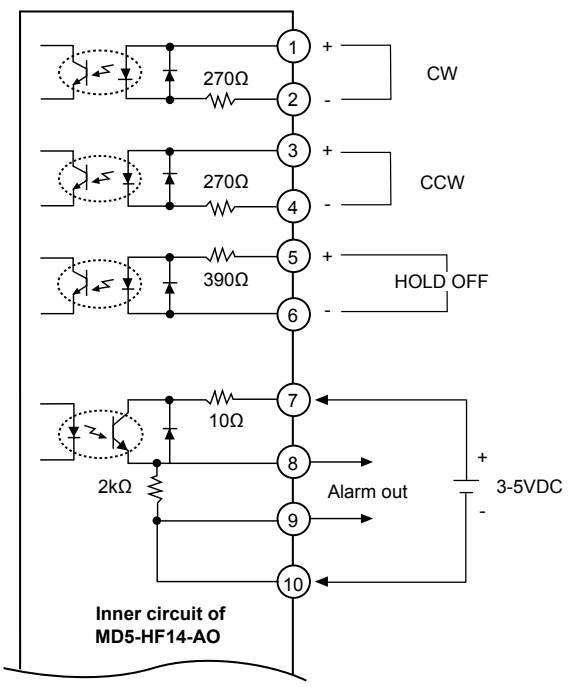
$$\text{Motor revolution angle (5-phase motors)} = \frac{\text{Basic step angle(0.72°)}}{\text{Resolution}}$$

※In case of geared motors, step angle shall be determined by dividing step angle by gear ratio.
EX) 0.72˚/ 10 (1:10) = 0.072˚
※It may cause step-out if resolution is changed while motor is running.

◎ ALRAM OUTPUT Function

※Overheat : When the temperature of inner driver (Base) is over 80℃, Alarm LED (Red) is turned ON and motor becomes HOLD OFF. Turn OFF the power, remove the causes, and re-supply the power to clear the alarm.
※Overcurrent : When overcurrent is applied to motor due to damage by a fire of stepper motor, broken of inner driver, or occurrence of abnormal error, Alarm LED (Red) flashes and motor becomes HOLD OFF. Turn OFF the power, remove the causes, and re-supply the power to clear the alarm.

▣ Input·Output diagram



※CW
2-pulse input mode - CW direction rotation pulse
1-pulse input mode - Operation command pulse input

※CCW
2-pulse input mode - CCW direction rotation pulse input
1-pulse input mode - Operation command pulse
[H] : CW, [L] : CCW

※HOLD OFF
Motor excitation OFF control signal
[H] : Motor excitation OFF

※When alarm occurs, it turns HOLD OFF. After cut off the power, remove the causes to operate normally.

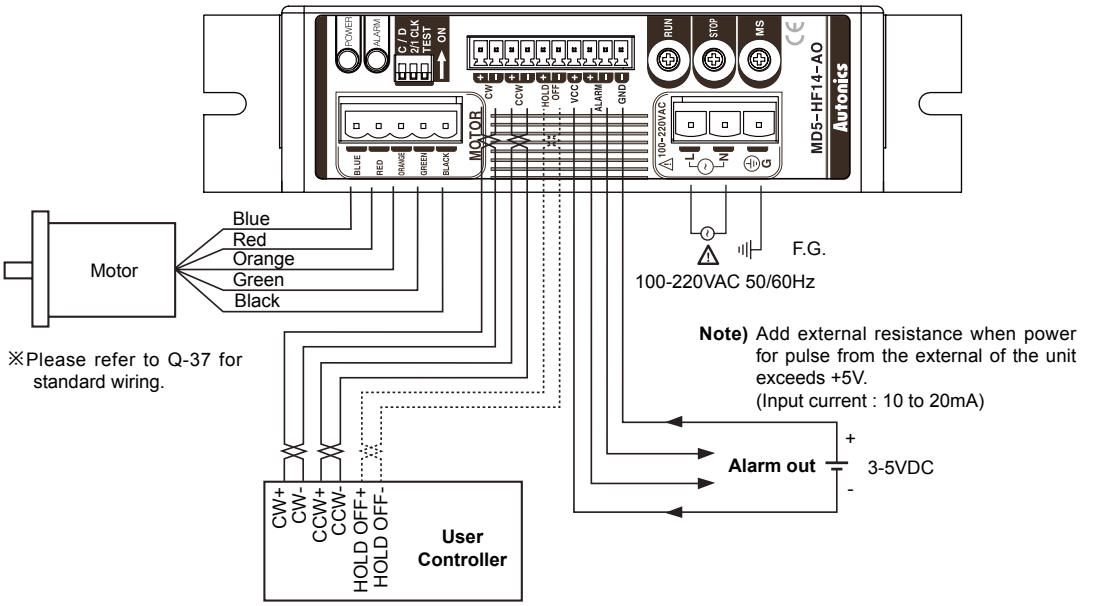
※Overheat :



※Over current :

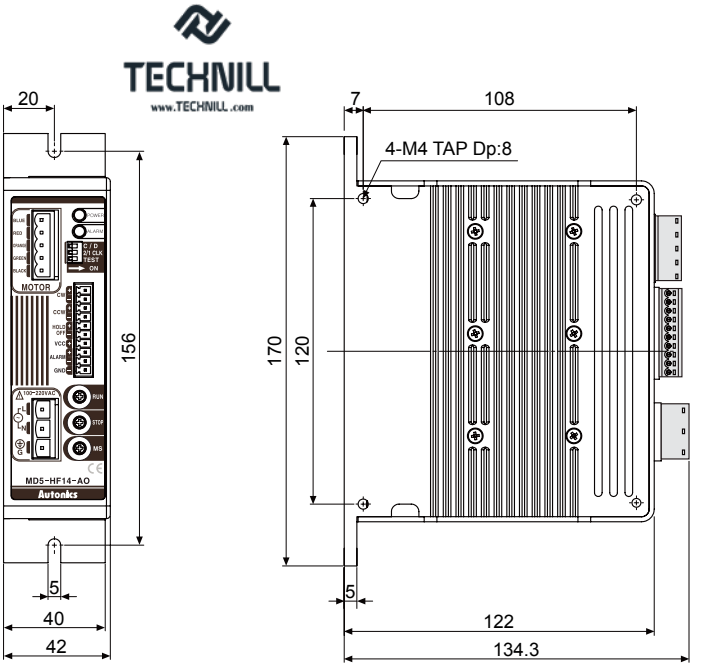


■ Connections



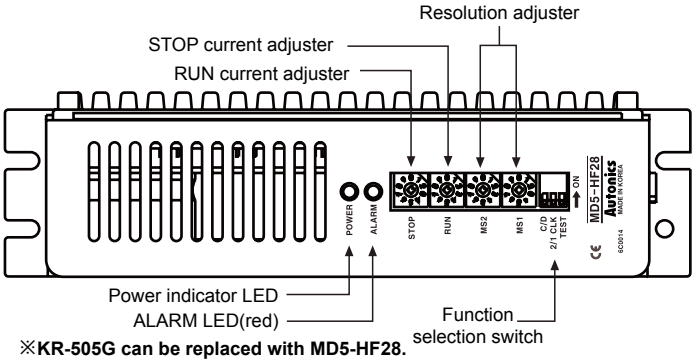
■ Dimensions

(unit: mm)



5-Phase Microstep motor driver [MD5-HF28]





※**KR-505G can be replaced with MD5-HF28.**
※**Power supply 100-220VAC and connected socket are upgraded.**

◎ Function selection switch



NO	Name	Function	Switch position	
			ON	OFF
1	TEST	Self-diagnosis	Rotate in 250Hz	—
2	2/1 CLK	Pulse input method	1 Pulse input	2 Pulse input
3	C/D	Auto current down	Not using	Using

●TEST
※Self-diagnosis function is to test motors and drivers.
※Motors rotate with 250Hz in full-step. Motor rotation speed is subject to change depending on resolution setting.
※Rotation speed = 30 rpm / resolution
※The motor will rotate in CCW direction when in 1-pulse input mode and in CW direction when in 2-pulse input mode.
Note) Make sure that TEST switch is set to OFF before supplying the power.
It may cause injury or danger if TEST switch is set to ON when power is supplied.

●2/1 CLK
※1/2 CLK switch is to select pulse input mode.
※1-pulse input mode : CW → operation command pulse input, CCW → rotation direction pulse input
([H]: CW rotation, [L]: CCW rotation)
※2-pulse input mode : CW → CW direction rotation pulse input, CCW → CCW direction rotation pulse input

●C/D (Auto current down)
※This function is reducing current automatically according to STOP current setting value in order to suppress generated heat when motor is stop
※It activates when there is no pulse input of motor operation for over 200ms.

◎ RUN current setting



Switch No.	0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F
Current (A/Phase)	1.14	1.25	1.36	1.50	1.63	1.74	1.86	1.97	2.10	2.20	2.30	2.40	2.50	2.60	2.78	2.88

※RUN current is a phase current provided to 5-phase stepper motor.
※Be sure to set RUN current at the rated current or below.
※Adjust the RUN current in case severe heat generation occurs. Be sure that torque decreasing may occur when adjusting the current.
Note) Be sure to adjust RUN current while motor is running.

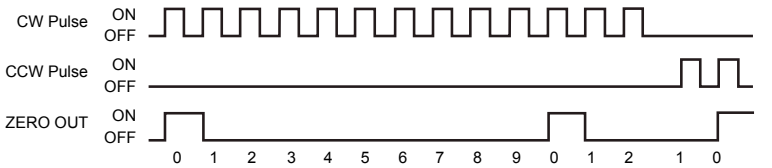
◎ STOP current setting



Switch No.	0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F
%	27	31	36	40	45	50	54	58	62	66	70	74	78	82	86	90

※STOP current is a phase current provided to 5-phase stepper motor at standstill.
※It will be activated when C/D (Auto current down) is set to ON. By setting STOP current, it is possible to suppress the heat generation at motor standstill.
※STOP current setting value is the ratio of RUN current setting value (%).
Ex) In case RUN current setting value is set to 1.4A and STOP current setting value is set to 50%, auto current down current is set to 0.7A.
※STOP current setting value may have some deviation depending on resistance impedance of motor.
※Auto current down function will be activated when HOLD OFF signal is [L]. When HOLD OFF signal is [H], the function is not activated since the current provided to each phase is cut off.
Note) Be sure to adjust STOP current while motor is at standstill.

◎ Zero point excitation output signal (ZERO OUT)



※ The signal is output to indicate when the motor excitation status is in the initial stage. / Used to check the rotation position of motor's axis

※In case of full step, the signal is output every 7.2°. (50 times / rotation)

EX) Full step (0.72°/Step) : Signal is output every 10 pulses.
20 divisions (0.036°/Step) : Signal is output every 200 pulses.

◎ HOLD OFF function

※When HOLD OFF input signal is [H], motor excitation is released.
When HOLD OFF input signal is [L], motor excitation is in a normal status.

※A function used to rotate motor's axis using external force or used for manual positioning.

※HOLD OFF Input signal [H] and [L] represent photocoupler ON/OFF in a circuit.

※Please do not use for stopping motor.

◎ Setting microstep(Microstep : Resolution)



Switch No.	0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F
Resolution	1	2	4	5	8	10	16	20	25	40	50	80	100	125	200	250
Step angle	0.72°	0.36°	0.18°	0.144°	0.09°	0.072°	0.045°	0.036°	0.0288°	0.018°	0.0144°	0.009°	0.0072°	0.00576°	0.0036°	0.00288°

● Resolution setting(Same as MS1, MS2)

※It is set to MS1 when division selection signal is [L], and MS2 when division selection signal is [H].

※Two different micro step can be set using DIVISION SELECTION. Users can select one of them via external input signals.

※Microstep is to make basic step angle of 5-phase motors (0.72°) divided into smaller angle according to setting values.

※The formula for microstep angle is ;

$$\text{Motor revolution angle (5-phase motors)} = \frac{\text{Basic step angle(0.72°)}}{\text{Resolution}}$$

※In case of geared motors, step angle shall be determined by dividing step angle by gear ratio.
EX) 0.72˚/ 10 (1:10) = 0.072˚

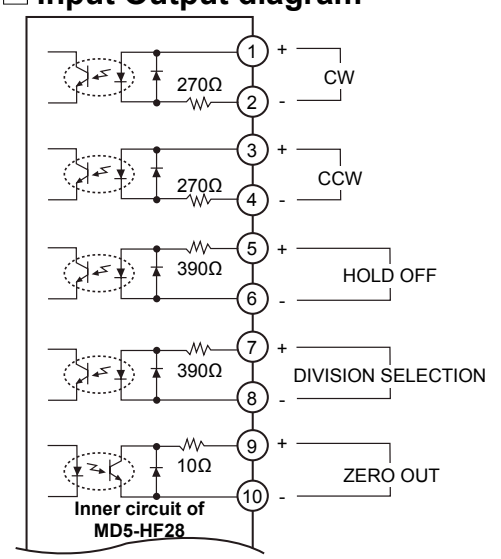
※It may cause step-out if resolution is changed while motor is running.

◎ ALRAM Function

※Over heat : When the temperature in driver BASE is over 80℃, Alarm LED will be ON and motor will stop with holding the torque. Remove the Over Heat Alarm causing factors and reset the power in order to reset alarm function

※Overcurrent : When overcurrent is applied to the motor due to driver damage or errors, Alarm LED will be flickering. In case of overcurrent, the motor will be HOLD OFF. Cut off the power and remove overcurrent-causing factors in order to resume normal operation.

▣ Input·Output diagram



※CW
2-pulse input mode - CW direction rotation pulse input
1-pulse input mode - Operation command pulse input

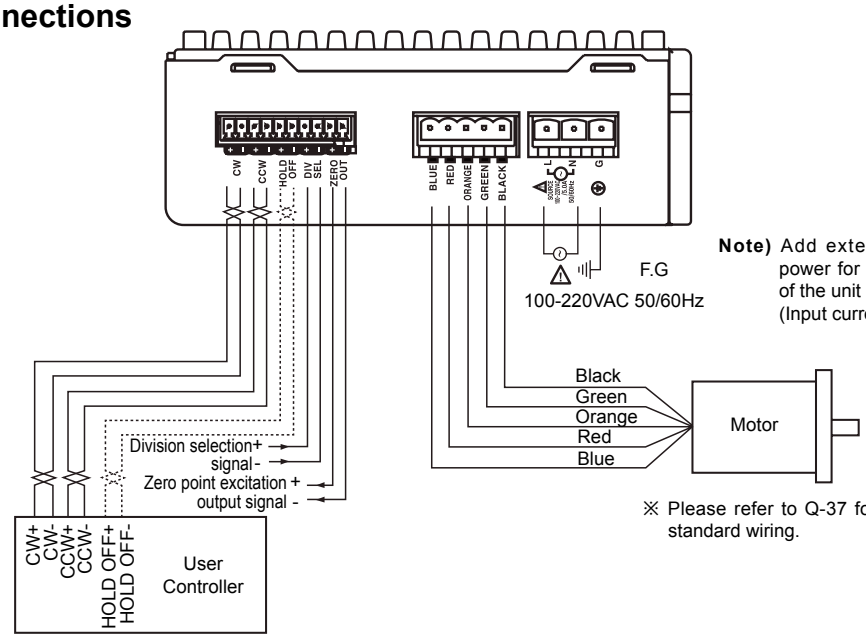
※CCW
2-pulse input mode - CCW direction rotation pulse input
1-pulse input mode - Rotation direction pulse input
[H] : CW, [L] : CCW

※HOLD OFF
Motor excitation OFF control signal
[H] : Motor excitation OFF

※DIVISION SELECTION
Division selection signal
→ [L] : Operated by MS1 setting resolution.
[H] : Operated by MS2 setting resolution.

※ZERO OUT
Zero point excitation output signal ON for zero point excitation

▣ Connections

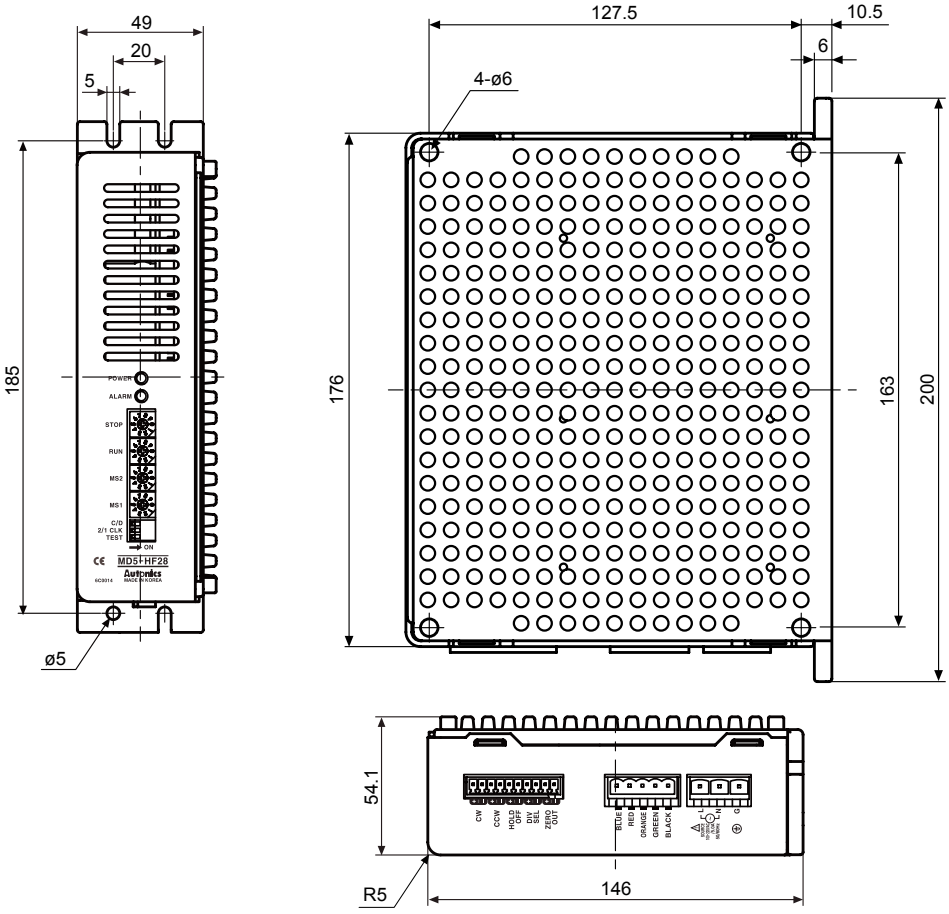


Note) Add external resistance when power for pulse from the external of the unit exceeds +5V. (Input current : 10 to 20mA)

※ Please refer to Q-37 for standard wiring.

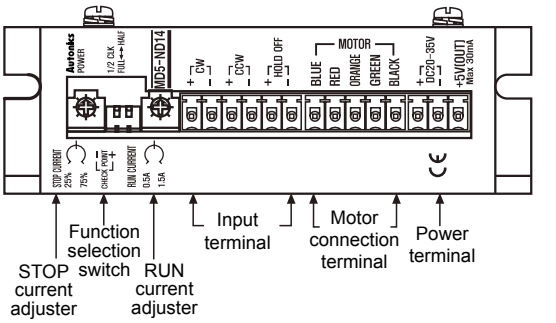
▣ Dimensions

(unit: mm)



5-Phase stepper motor driver [MD5-ND14]





◎ Function selection switch



NO	Name	Function	Switch position	
			ON	OFF
1	1/2 CLK	Pulse input method	1 Pulse input	2 Pulse input
2	FULL ↔ HALF	Resolution Setting	0.72°	0.36°

● 1/2 CLK

※1/2 CLK switch is to select pulse input mode.
※1-pulse input mode : CW → operation command pulse input, CCW → rotation direction pulse input
([H]: CW rotation, [L]: CCW rotation)
※2 Pulse input mode : CW → CW direction rotation pulse input, CCW → CCW direction rotation pulse input

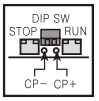
● FULL ↔ HALF

※FULL ↔ HALF switch is to select pulse input mode.
※If changing resolution while the motor is running, it may cause step-out.

◎ RUN current setting



※RUN current is a phase current provided to 5-phase stepper motor.
※Be sure to set RUN current at the rated current or below.
※RUN current setting range: 0.5 to 1.5A
※When changing RUN current, connect CP+ to voltmeter (+) terminal and CP- to voltmeter (-) terminal, then adjust the volume.



※The formula for phase-current setting is ;

$$\text{Setting current(A)} = \frac{\text{CP Input Voltage(V)}}{2}$$

※Adjust the RUN current in case severe heat generation occurs. Be sure that torque decreasing may occur when adjusting the current.
Note) Be sure to adjust RUN current while motor is running.

◎ STOP current setting

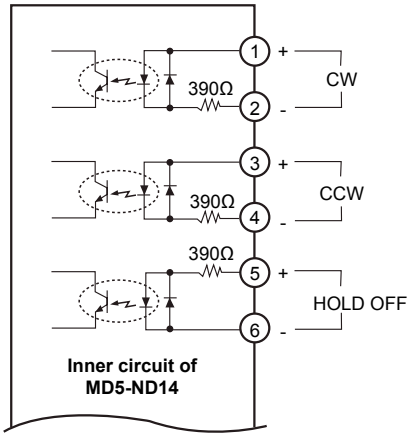


※STOP current is a phase current provided to 5-phase stepper motor at standstill.
※A function to reduce the current in order to suppress the heat generation at motor standstill / STOP current setting range : 25 to 75% of RUN current using VR
※In case Run current setting value is set to 1.0A and STOP current setting value is set to 50%, STOP current is set to 0.5A.
※STOP current setting value may have some deviation depending on resistance impedance of motor.
※STOP current function will be activated when HOLD OFF signal is [L]. When HOLD OFF signal is [H], the function is not activated since the current provided to each phase is cut off.
※STOP current function will be activated when no operation command pulse is input within 500ms.
Note) Be sure to adjust STOP current while motor is at standstill.

◎ HOLD OFF function

※When HOLD OFF input signal is [H], motor excitation is released.
When HOLD OFF input signal is [L], motor excitation is in a normal status.
※A function used to rotate motor's axis using external force or used for manual positioning.
※HOLD OFF Input signal [H] and [L] represent photocoupler ON/OFF in a circuit.
※Please do not use for stopping motor.

▣ Input diagram

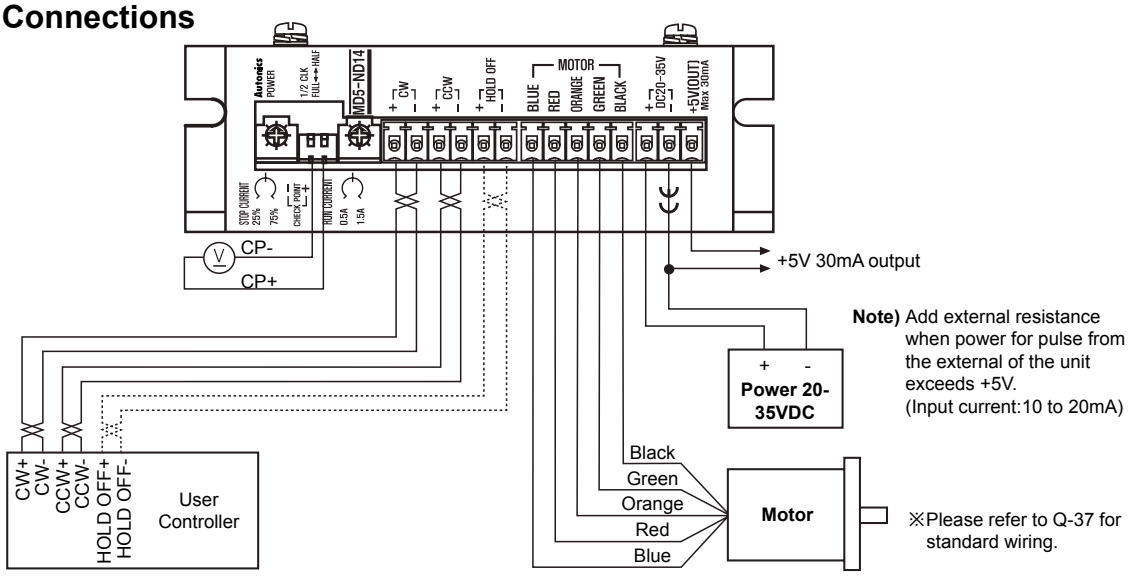


※CW
2 pulse input method(CW direction rotation pulse input)
1 pulse input method(Operating command pulse input)
Note) If the power for driving pulse from external is over than +5V, please connect resistor

※CCW
2 pulse input method(CCW direction rotation pulse input)
1 pulse input method(Rotating direction pulse input)
→ [H] : CW, [L] : CCW

※HOLD OFF
The control signal for hold off of Motor → [H] : Motor Hold OFF

▣ Connections



Note) Add external resistance when power for pulse from the external of the unit exceeds +5V.
(Input current:10 to 20mA)

※Please refer to Q-37 for standard wiring.

▣ Dimensions

(unit: mm)

